

# Announcements

1) No more Webwork!

Which matrix goes first?

Start with a matrix  $A$ .

If  $A$  is diagonalizable,

then there exists a

diagonal matrix  $D$

and an invertible

matrix  $S$  with

$$S^{-1}AS = D$$

Let  $\lambda_1, \lambda_2, \dots, \lambda_n$  be the eigenvalues of  $A$  and  $v_1, v_2, \dots, v_n$  the associated eigenvectors.

Then  $A$  is "diagonal" with respect to  $\{v_1, v_2, \dots, v_n\}$  in the

sense that

$$A v_i = \lambda_i v_i$$

for  $1 \leq i \leq n$ .

$$\text{Let } S = \begin{bmatrix} v_1 & v_2 & \cdots & v_n \end{bmatrix}.$$

How do we know this is  
 $S$  and not  $S^{-1}$ ?

We know

$$D = \begin{bmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \end{bmatrix}$$

$$\boxed{D e_i = \lambda_i e_i}$$

$$S e_i$$

$$= \begin{bmatrix} v_1 & v_2 & \dots & v_n \end{bmatrix} e_i$$

$$= i^{\text{th}} \text{ column of } S$$


$$= v_i$$

$$\begin{aligned} & A S e_i \\ &= A (S e_i) \\ &= A v_i \\ &= \lambda_i v_i \end{aligned}$$

$$\begin{aligned} & S^{-1} A S e_i \\ &= S^{-1} (A S e_i) \\ &= S^{-1} (\lambda_i v_i) \\ &= \lambda_i S^{-1} v_i = \lambda_i e_i \end{aligned}$$

# Picture

$$e_i \xrightarrow{S} v_i \xrightarrow{A} \lambda_i v_i \xrightarrow{S^{-1}} \lambda_i e_i$$


$$= S^{-1} A S$$

Example 1: Diagonalize

$$A = \begin{bmatrix} -2 & 56 \\ 56 & 11 \end{bmatrix}$$

$$\lambda_1 = \frac{1}{2} (9 + \sqrt{12713})$$

$$\lambda_2 = \frac{1}{2} (9 - \sqrt{12713})$$

$$v_1 = \begin{bmatrix} \frac{1}{112} (-13 + \sqrt{12713}) \\ 1 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} \frac{1}{112} (-13 - \sqrt{12713}) \\ 1 \end{bmatrix}$$



In this case

$$S = \begin{bmatrix} v_1 & v_2 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{\sqrt{2}} (-13 + \sqrt{12713}) & \frac{1}{\sqrt{2}} (-13 - \sqrt{12713}) \\ & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} \frac{1}{2} (9 + \sqrt{12713}) & 0 \\ 0 & \frac{1}{2} (9 - \sqrt{12713}) \end{bmatrix}$$

$$\boxed{S^{-1}AS = D}$$

# Eigenvalues of Special Matrices

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Let  $A$  be  $n \times n$ .

1) If  $(Av) \cdot v \geq 0$ ,

then all eigenvalues  
of  $A$  are non-negative.

We call such an  $A$   
positive semi-definite.

2) If  $A^t A = I_n$ ,

then all eigenvalues  
of  $A$  are either

1 or  $-1$ . We

call such a matrix

**Orthogonal**. We call

$A$  this because the

condition implies the

rows of  $A$  are all orthogonal  
to each other and the columns  
of  $A$  are orthogonal to each other.

# Diagonalization

When can we diagonalize an  $n \times n$  matrix  $A$ ?

Precisely when  $A$  has

$n$  linearly independent

eigenvectors! IF

$v_1, v_2, \dots, v_n$  are these

eigenvectors corresponding

to  $\lambda_1, \lambda_2, \dots, \lambda_n$ ,

respectively, then

$$S^{-1}AS = D$$

where  $S = [v_1 v_2 \dots v_n]$

$$D = \begin{bmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \end{bmatrix}.$$

# The symmetric case

Definition: An  $n \times n$  matrix

$A$  is called **symmetric**

if  $A = A^t$ .

# Existence of Eigenvalues for Symmetric Matrices

Let  $A$  be  $2 \times 2$ ,  $A = A^t$ .

$$A = \begin{bmatrix} a & b \\ b & c \end{bmatrix}.$$

$$\det(A - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix})$$

$$= \det \begin{pmatrix} a - \lambda & b \\ b & c - \lambda \end{pmatrix}$$

$$= \lambda^2 - (a+c)\lambda + ac - b^2 = 0$$

$$\lambda^2 - (a+c)\lambda + ac - b^2 = 0$$

Using quadratic formula,

$$\lambda = \frac{(a+c) \pm \sqrt{(a+c)^2 - 4ac + 4b^2}}{2}$$

Can this be imaginary?

$$\begin{aligned} & (a+c)^2 - 4ac + 4b^2 \\ &= a^2 + 2ac + c^2 - 4ac + 4b^2 \\ &= a^2 - 2ac + c^2 + 4b^2 \end{aligned}$$



$$= (a-c)^2 + 4b^2$$

$$\underline{\geq 0} \quad \text{always!}$$

So  $A$  only has  
real eigenvalues!

To go to the  
 $n \times n$  symmetric  
matrices, we use

mathematical induction.

Use  $n=1$  to prove  $n=2$  then

Use  $n=2$  to prove  $n=3$  then

Use  $n=3$  to prove  $n=4$  then

Continue!

# Orthogonal Diagonalization

If  $A$  is symmetric,

$$\text{then } S^{-1}AS = D$$

for  $S$  satisfying

$$S^t S = I_n \text{ (orthogonal)}$$

Then  $S^{-1} = S^t$ , so

$$\boxed{S^t A S = D}$$

To get this, let's show

that if  $\lambda_1 \neq \lambda_2$

are two eigenvalues of  $A$

where  $A = A^t$ , then if

$$A v_1 = \lambda_1 v_1 \text{ and } A v_2 = \lambda_2 v_2,$$

we must have  $v_1 \cdot v_2 = 0$ .

Fact: I have new pen colors.

But the relevant fact is  
that for all  $v, w$  in  $\mathbb{R}^n$ ,

$$(Av) \cdot w = v \cdot (A^t w).$$

Then if  $\lambda_1 = 0$ , we have

$\lambda_2 \neq 0$ , and

$$v_1 \cdot v_2 = v_1 \cdot \left( \frac{\lambda_2}{\lambda_2} v_2 \right)$$

$$= \frac{1}{\lambda_2} v_1 \cdot (\lambda_2 v_2)$$

$$= \frac{1}{\lambda_2} v_1 \cdot (A v_2)$$

$$= \frac{1}{\lambda_2} v_1 \cdot (A^t v_2)$$

(since  $A = A^t$ )

$$= \frac{1}{\lambda_2} (A v_1) \cdot v_2$$

$$= \frac{1}{\lambda_2} \vec{0} \cdot v_2 = 0 \quad \checkmark$$

If  $\lambda_1 \neq 0$ , then

$$v_1 \cdot v_2 = \left( \frac{\lambda_1}{\lambda_1} v_1 \right) \cdot v_2$$

$$= \frac{1}{\lambda_1} (\lambda_1 v_1) \cdot v_2$$

$$= \frac{1}{\lambda_1} (A v_1) \cdot v_2$$

$$= \frac{1}{\lambda_1} v_1 \cdot (A^t v_2)$$

$$= \frac{1}{\lambda_1} v_1 \cdot (A v_2) \quad (A = A^t)$$

$$= \frac{1}{\lambda_1} v_1 \cdot (\lambda_2 v_2)$$

$$= \frac{\lambda_2}{\lambda_1} (v_1 \cdot v_2)$$

Then subtracting

$$\frac{\lambda_2}{\lambda_1} (v_1 \cdot v_2),$$

$$v_1 \cdot v_2 - \left(\frac{\lambda_2}{\lambda_1}\right) v_1 \cdot v_2 = 0$$

$$\text{so } (v_1 \cdot v_2) \left(1 - \frac{\lambda_2}{\lambda_1}\right) = 0.$$

This means either  $v_1 \cdot v_2 = 0$

or  $1 - \frac{\lambda_2}{\lambda_1} = 0$ . But we know

$\lambda_2 \neq \lambda_1$ , so  $1 - \frac{\lambda_2}{\lambda_1} \neq 0$ , and

then we must have  $v_1 \cdot v_2 = 0$  ✓



Problem: What if  $\lambda_1 = \lambda_2 = \lambda$ ?

Then the subspace of all  $v$  in  $\mathbb{R}^n$  with  $Av = \lambda v$

is at least two dimensional,

so we can choose  $v_1$  and  $v_2$

with  $v_1 \cdot v_2 = 0$  in this

subspace.

We can then get

$$v_i \cdot v_j = 0 \text{ for all } i \neq j.$$

By dividing by  $\|v_i\|_2$ , we may assume  $\|v_i\|_2 = 1$ , and

$$\text{so } S = [v_1 \ v_2 \ \cdots \ v_n]$$

satisfies  $S^t S = I_n$ .